Introduction to High Performance Computing

SDS406 – Fall semester, 2024 - 2025

L10: MPI custom types and MPI-I/O, 2nd December 2024

- So far, we parallelized in the slowest running index (y) which meant that we needed to communicate continuous elements of the arrays between neighbors.
- Now we will consider parallelizing of the heat equation in the χ dimension
	- We need to communicate the boundaries of $\bm{\mathsf{y}}$
	- This means we need to communicate *non-contiguous* elements

- So far, we parallelized in the slowest running index (y) which meant that we needed to communicate continuous elements of the arrays between neighbors.
- Now we will consider parallelizing of the heat equation in the χ dimension
	- We need to communicate the boundaries of $\bm{\mathsf{y}}$
	- This means we need to communicate *non-contiguous* elements

- So far, we parallelized in the slowest running index (y) which meant that we needed to communicate continuous elements of the arrays between neighbors.
- Now we will consider parallelizing of the heat equation in the χ dimension
	- We need to communicate the boundaries of $\bm{\mathsf{y}}$
	- This means we need to communicate *non-contiguous* elements

Could use temporary arrays to copy boundaries before communication

- So far, we parallelized in the slowest running index (y) which meant that we needed to communicate continuous elements of the arrays between neighbors.
- Now we will consider parallelizing of the heat equation in the χ dimension
	- We need to communicate the boundaries of $\bm{\mathsf{y}}$
	- This means we need to communicate *non-contiguous* elements

- Could use temporary arrays to copy boundaries before communication
- Alternatively, so-called **custom MPI types**

- MPI_DOUBLE, MPI_FLOAT, MPI_INT, etc. are pre-defined MPI types
- User-defined types allow for custom data types
- Using types with *strides* provides for a convenient way to arrange sending and receiving non-continuous data

- MPI_DOUBLE, MPI_FLOAT, MPI_INT, etc. are pre-defined MPI types
- User-defined types allow for custom data types
- Using types with *strides* provides for a convenient way to arrange sending and receiving non-continuous data

MPI Vector type

int MPI_Type_vector(int count, int blocklength, int stride, MPI_Datatype oldtype, MPI_Datatype *newtype)

- MPI_DOUBLE, MPI_FLOAT, MPI_INT, etc. are pre-defined MPI types
- User-defined types allow for custom data types
- Using types with *strides* provides for a convenient way to arrange sending and receiving non-continuous data

MPI Vector type

int MPI_Type_vector(int count, int blocklength, int stride, MPI_Datatype oldtype, MPI_Datatype *newtype)

- One of the most basic ways to create a custom MPI type
- The following corresponds to the figure
	- \rightarrow pick the 6 highlighted elements from the 24-element array

MPI_Datatype dtype; MPI_Type_vector(3, 2, 8, MPI_DOUBLE, &dtype); MPI Type commit(&dtype);

• Can then specify this new type in MPI functions \rightarrow e.g. in an <code>MPI_Send()</code>

MPI_Send(&a[0], 1, dtype, dest, tag, MPI_COMM_WORLD);

MPI Vector type

- See ex01:
	- \circ The root process initializes an array of L elements, r[L]
	- All processes post a non-blocking receive (MPI_Irecv()) for L/nproc elements
	- The root process will send L/nproc elements to each process, one-by-one, in a loop
	- We would like:
		- rank 0 to receive the elements: $r[0]$, $r[nnroc-1]$, $r[2*nproc-1]$, etc.
		- rank 1 to receive the elements: $r[1], r[$ nproc], $r[$ 2*nproc], etc.
		- rank 2 to receive the elements: $r[2]$, $r[nnroc+1]$, $r[2*nproc+1]$, etc.
		- and so on

MPI Vector type

- See ex01:
	- \circ The root process initializes an array of L elements, $r[L]$
	- All processes post a non-blocking receive (MPI_Irecv()) for L/nproc elements
	- The root process will send L/nproc elements to each process, one-by-one, in a loop
	- We would like:
		- rank 0 to receive the elements: $r[0]$, $r[nnroc-1]$, $r[2*nproc-1]$, etc.
		- rank 1 to receive the elements: $r[1], r[$ nproc], $r[$ 2*nproc], etc.
		- rank 2 to receive the elements: $r[2]$, $r[nnroc+1]$, $r[2*nproc+1]$, etc.
		- **and so on**

/***

* TODO: Define the new datatype that strides by `nproc' elements ***/ MPI_Datatype dtype; MPI Type vector($/*$ TODO $*/$); MPI_Type_commit(&dtype);

Binary vs text *//* Binary I/O *//* Parallel I/O with MPI

- So far we have been writing files as *formatted text*
- This requires *converting* the internal, binary representation of floating point numbers into *human readable* representations, e.g. as characters, using a specific encoding, usually *ASCII*
- However, the more general and flexible way to store data is in *binary*. This allows storing data of multiple types, multidimensional data, etc.
- Think of it as storing the same binary data as in a memory buffer to a file

- So far we have been writing files as *formatted text*
- This requires *converting* the internal, binary representation of floating point numbers into *human readable* representations, e.g. as characters, using a specific encoding, usually *ASCII*
- However, the more general and flexible way to store data is in *binary*. This allows storing data of multiple types, multidimensional data, etc.
- Think of it as storing the same binary data as in a memory buffer to a file

```
double x[L];
/* Fill x[] */FILE *fp = fopen("filename", "w");
fwrite(&x[0], sizeof(double), L, fp);
fclose(fp);
```
double y[L]; FILE $*fp = fopen("filename", "r")$; fread(&y[0], sizeof(double), L, fp); fclose(fp); /* Do something with $y[]$ */

- In Python, the struct module can be used to convert to/from a byte string
- Alternatively you can use numpy and the numpy.fromfile() function

```
import struct
```

```
fp = open("out", "br")
r = fp.read()fp.close()
n = len(r)//8
r = struct.unpack(n*"d", r)
```
import numpy as np

```
r = np.fromfile("out", dtype=np.float64)
```
- In Python, the struct module can be used to convert to/from a byte string
- Alternatively you can use numpy and the numpy.fromfile() function

```
import struct
```

```
fp = open("out", "br")
r = fp.read()fp.close()
n = len(r)/8r = struct.unpack(n*"d", r)
```

```
import numpy as np
```

```
r = np.fromfile("out", dtype=np.float64)
```
- Inspecting files on the command line:
	- The Linux commands more and less interpret files as *text*. A text file is still a binary file, but its contents are intended to be interpreted as characters
	- The Linux command od can be used to interpret files in other formats, e.g. octal, hexadecimal, floating point, etc. in addition to text. od stands for "Octal dump".

- In Python, the struct module can be used to convert to/from a byte string
- Alternatively you can use numpy and the numpy.fromfile() function

```
import struct
```

```
fp = open("out", "br")
r = fp.read()fp.close()
n = len(r)/8r = struct.unpack(n*"d", r)
```

```
import numpy as np
```

```
r = np.fromfile("out", dtype=np.float64)
```
- Inspecting files on the command line:
	- The Linux commands more and less interpret files as *text*. A text file is still a binary file, but its contents are intended to be interpreted as characters
	- o The Linux command od can be used to interpret files in other formats, e.g. octal, hexadecimal, floating point, etc. in addition to text. od stands for "Octal dump".
- See ex02 which contains some examples demonstrating binary read/write

Variants:

- "Non-parallel" I/O: all send to one rank, which carries out I/O \leftarrow our approach so far, with the exception of the heat equation example
- Independent parallel I/O: each rank writes/reads to/from its own file
- "Cooperative" parallel I/O: each rank writes/reads to/from different parts of the same file

Variants:

- "Non-parallel" I/O: all send to one rank, which carries out I/O \leftarrow our approach so far, with the exception of the heat equation example
- Independent parallel I/O: each rank writes/reads to/from its own file
- "Cooperative" parallel I/O: each rank writes/reads to/from different parts of the same file

Cooperative parallel I/O

- Requires parallelism aware software layer (MPI-I/O)
- Performance depends on underlying hardware and filesystem
- In MPI context
	- Writing to a file \Leftrightarrow sending a buffer
	- Reading from a file \Leftrightarrow receiving a buffer

Variants:

- "Non-parallel" I/O: all send to one rank, which carries out I/O \leftarrow our approach so far, with the exception of the heat equation example
- Independent parallel I/O: each rank writes/reads to/from its own file
- "Cooperative" parallel I/O: each rank writes/reads to/from different parts of the same file

Cooperative parallel I/O

- Requires parallelism aware software layer (MPI-I/O)
- Performance depends on underlying hardware and filesystem
- In MPI context
	- Writing to a file \Leftrightarrow sending a buffer
	- Reading from a file \Leftrightarrow receiving a buffer
- This means custom types can be used in the same way as in MPI_Send() and MPI_Recv
	- When writing a custom type can be used to pick out specific elements of the array to be written
	- When reading it can be used to pick the specific elements of the array to be filled
- Extensive use of custom MPI types is also typically used to set "file views". These determine which parts of the file will be picked to be read or written.

MPI_File_open, MPI_File_write_at, MPI_File_write_all, etc.

int MPI_File_open(MPI_Comm comm, const char *filename, int amode, MPI_Info info, MPI File \star fh)

Example:

MPI File fh; MPI_File_open(MPI_COMM_WORLD, "out", MPI_WRONLY | MPI_CREATE, MPI_INFO_NULL, &fh)

- Open file with filename out in write-only mode; create if it does not exist
- Options for amode: MPI_MODE_APPEND, MPI_MODE_CREATE, MPI_MODE_DELETE_ON_CLOSE, MPI_MODE_EXCL, MPI_MODE_RDONLY, MPI_MODE_RDWR, MPI_MODE_SEQUENTIAL, MPI_MODE_WRONLY, MPI_MODE_UNIQUE_OPEN

Use MPI_File_write_at() and MPI_File_read_at() write or read different parts of a file according to an offset.

int MPI_File_write_at(MPI_File fh, MPI_Offset offset, const void *buf, $\overline{}$ int count, MPI_Datatype datatype, MPI_Status *status)

E.g. see ex03

- o Each rank allocates and fills an array of N random numbers
- MPI_File_write_at() is used to write the data into a file, in order of the ranks

Use MPI_File_write_at() and MPI_File_read_at() write or read different parts of a file according to an offset.

int MPI_File_write_at(MPI_File fh, MPI_Offset offset, const void *buf, int count, MPI_Datatype datatype, MPI_Status *status)

- E.g. see ex03
	- o Each rank allocates and fills an array of N random numbers
	- MPI_File_write_at() is used to write the data into a file, in order of the ranks

File views

- File views determine which part of the file each process can see
- Same machinery as in sending/receiving custom types, e.g. using vector types with strides, etc.

int MPI_File_set_view(MPI_File fh, MPI_Offset disp, MPI_Datatype etype, MPI_Datatype filetype, const char *datarep, MPI_Info info)

- \circ etype: the element type (e.g. MPI_DOUBLE)
- filetype: the type used for the file view. Determines which part of the file the rank can "view"
- datarep: use "native" unless there is a need to explicitly set a different data representation
- \bullet In case we are writing to a file:
	- Think of the filetype as the custom type on the buffer of the receiving rank (which is now the file we are writing to)
	- Think of the MPI_File_write() call as the same as an MPI_Send()

File views

- ex04 demonstrate the basic use of a "file view"
- Start nproc processes
- \bullet Each rank allocates and fills N double precision numbers
	- \circ Rank 0 fills it with $1.0, 2.0, ..., N-1$,
	- \circ Rank 1 fills it with N, N+1, ..., 2*N-1
	- o etc.
- We want the file to be written such that:
	- The first nproc elements in the file are the first elements of all processes
	- The next nproc elements in the file are the second elements of all processes
	- o etc.

File views

- ex04 demonstrate the basic use of a "file view"
- Start nproc processes
- \bullet Each rank allocates and fills N double precision numbers
	- \circ Rank 0 fills it with 1.0, 2.0, ..., N-1,
	- \circ Rank 1 fills it with N, N+1, ..., 2*N-1
	- o etc.
- We want the file to be written such that:
	- The first nproc elements in the file are the first elements of all processes
	- The next nproc elements in the file are the second elements of all processes
	- o etc.

The heat equation program with parallelization over the χ -coordinate and MPI-I/O

Exercise ex05**, with missing parts marked as** TODO**s**

- Communication of the non-contiguous elements can be achieved using a vector custom data type
- Writing the non-contiguous elements to a binary file in parallel using MPI-I/O and file views
- \bullet The included plot.py takes care of reading from a binary file but is otherwise the same as before

* TODO_1 / #define IDX(y, x)

```
* TODO_1
 \star/#define IDX(y, x)
```

```
* Set the boundary condition for v[L*(lx+2)]
***/
void
boundary_condition(double *v)
 int size, rank;
 MPI_Comm_rank(MPI_COMM_WORLD, &rank);
 MPI_Comm_size(MPI_COMM_WORLD, &size);
   * TODO_2
   \star/* Which rank has x = 0?
   \star/if(rank = /* */) {
   * Which rank has x = L-1?
   \star/if(rank = /* */) {
   * Set y = L/2 to 1
   \star/
```

```
/***
 * Update the boundary of v[L*(lx+2)], by exchanging "halos"
***/
void
update_boundary(double *v)
{
  int size, rank;
  MPI_Comm_size(MPI_COMM_WORLD, &size);
  MPI_Comm_rank(MPI_COMM_WORLD, &rank);
  /\star* TODO_3
   \star/MPI_Datatype dtype;
  MPI_Type_vector(\nmid * \dots * \nmid);
  MPI_Type_commit(&dtype);
  /* Send x = 0 boundary to lx+1 of backward neighbor */MPI_Sendrecv( * . /);
  /* Send x = 1x-1 boundary to -1 of forward neighbor */MPI\_Sender (\n \frac{\star}{\cdot} \dots \frac{\star}{\cdot});
```
MPI-I/O and combining two custom types

- Use MPI-I/O to write the resulting array in parallel
- Need two custom types: one for the "file view" and one for the "data view"

MPI-I/O and combining two custom types

- Use MPI-I/O to write the resulting array in parallel
- Need two custom types: one for the "file view" and one for the "data view"

